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Information Disclosure	Applicant	STEARNS et al.
Statement By Applicant	Filing Date	June 25, 2003
	Group	3768
(Use Several Sheets if Necessary)		Page 1 of 1

U.S. Patent Documents

Examiner Initial	No.	Patent No.	Date	Patentee	Class	Sub- class	Filing Date
	1.						
	2.						
	3.						
	4.						
	5.						

Foreign Patent or Published Foreign Patent Application

Examiner Initial		Document No.	Publicatio n Date	Country or Patent Office	Class	Sub- Class	Translat Yes No	_
	6.							
	7.							
	8.							
	9.							

Other Documents

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Initial	No.	Author, Title, Place (e.g. Journal) of Publication, Date
	10.	MOUADDIB et al., "Recent Progress in Structured Light in Order to Solve the Correspondence Problem in Stereo Vision", International Conference of Robotics and Automation, Albuquerque, New Mexico, April 1997 pps. 130-136
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	12.	FOFI et al., "Uncalibrated Vision Based on Structured Light", Proceedings of the 2001 IEEE International Conference on Robotics and Automation, Seoul, Korea, May 2001, pps. 3548-3553
	13.	SCHARSTEIN et al., "High-Accuracy Stereo Depth Maps Using Structured Light", IEEE Computer Society Conference on Computer Vision and Pattern Recognition (CVPR) 2003), Vol. 1, Madison, Wisconsin, pps. 195-202
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Examiner /Vani Gupta/ Date Considered 08/1	13/2009
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Examiner: Initial citation considered. Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.

ALL REFERENCES CONSIDERED EXCEPT WHERE LINED THROUGH. /V.G./